

Question 13 Solution

$$\begin{aligned} \text{a)} \quad & x + 2y - z = 2 \\ & x + y + z = 3 \\ & 3x + 2y + z = 1 \end{aligned}$$

In matrix form the system is $\underline{A}\underline{X} = \underline{Y}$ where
 $\underline{A} = \begin{pmatrix} 1 & 2 & -1 \\ 1 & 1 & 1 \\ 3 & 2 & 1 \end{pmatrix}$, $\underline{X} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ and $\underline{Y} = \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix}$

The augmented matrix for the system is $\left(\begin{array}{ccc|c} 1 & 2 & -1 & 2 \\ 1 & 1 & 1 & 3 \\ 3 & 2 & 1 & 1 \end{array} \right)$

Using the method of row reduction:

$$\left. \begin{aligned} R_1' &= R_1 \\ R_2' &= R_2 - R_1 \\ R_3' &= R_3 - 3R_1 \end{aligned} \right\} \rightarrow \left(\begin{array}{ccc|c} 1 & 2 & -1 & 2 \\ 0 & -1 & 2 & 1 \\ 0 & -4 & 4 & -5 \end{array} \right)$$

$$\left. \begin{aligned} R_1' &= R_1 \\ R_2' &= R_2 \\ R_3' &= R_3 - 4R_2 \end{aligned} \right\} \rightarrow \left(\begin{array}{ccc|c} 1 & 2 & -1 & 2 \\ 0 & -1 & 2 & 1 \\ 0 & 0 & -4 & -9 \end{array} \right)$$

$$\text{So } -4z = -9 \rightarrow z = \frac{9}{4}$$

$$-y + 2z = 1 \rightarrow y = \frac{9}{2} - 1 = \frac{7}{2}$$

$$x + 2y - z = 2 \rightarrow x = 2 + \frac{9}{4} - 7 = -\frac{11}{4}$$

Hence the solution is

$$\underline{x = -\frac{11}{4}, \quad y = \frac{7}{2}, \quad z = \frac{9}{4}}$$

13b

$$x + y + 4z = 3$$

$$2x + y + 2z = 4$$

$$3x + y = 5$$

In matrix form the system is $\underline{A}\underline{X} = \underline{Y}$ where

$$\underline{A} = \begin{pmatrix} 1 & 1 & 4 \\ 2 & 1 & 2 \\ 3 & 1 & 0 \end{pmatrix}, \quad \underline{X} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}, \quad \underline{Y} = \begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix}.$$

The augmented matrix of the system is $\left(\begin{array}{ccc|c} 1 & 1 & 4 & 3 \\ 2 & 1 & 2 & 4 \\ 3 & 1 & 0 & 5 \end{array} \right)$

Using the method of row reduction:

$$\left. \begin{array}{l} R_1' = R_1 \\ R_2' = R_2 - 2R_1 \\ R_3' = R_3 - 3R_1 \end{array} \right\} \rightarrow \left(\begin{array}{ccc|c} 1 & 1 & 4 & 3 \\ 0 & -1 & -6 & -2 \\ 0 & -2 & -12 & -4 \end{array} \right)$$

$$\left. \begin{array}{l} R_1' = R_1 \\ R_2' = R_2 \\ R_3' = R_3 - 2R_2 \end{array} \right\} \rightarrow \left(\begin{array}{ccc|c} 1 & 1 & 4 & 3 \\ 0 & -1 & -6 & -2 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

One of the equations is redundant, therefore there will be an infinite set of solutions.

$$\begin{array}{lcl} -y - 6z = -2 & \rightarrow & y = 2 - 6z \\ x + y + 4z = 3 & \rightarrow & x = 3 - (2 - 6z) - 4z = 1 + 2z \end{array}$$

Hence the set of solutions is

$$\underline{x = 1 + 2t, \quad y = 2 - 6t, \quad z = t \quad \text{for } -\infty < t < \infty}$$

Question 14 Solution

The eigenvalues of the matrix A are the solutions of the determinantal equation $\det(\underline{A} - \lambda \underline{I}) = 0$.

So if $\underline{A} = \begin{pmatrix} 2 & -3 & 1 \\ -3 & 6 & -3 \\ 1 & -3 & 2 \end{pmatrix}$ we need to solve $\begin{vmatrix} 2-\lambda & -3 & 1 \\ -3 & 6-\lambda & -3 \\ 1 & -3 & 2-\lambda \end{vmatrix} = 0$

$$\left. \begin{array}{l} R_1' = R_1 - R_3 \\ R_2' = R_2 \\ R_3' = R_3 \end{array} \right\} \rightarrow \begin{vmatrix} 1-\lambda & 0 & -1+\lambda \\ -3 & 6-\lambda & -3 \\ 1 & -3 & 2-\lambda \end{vmatrix} = (1-\lambda) \begin{vmatrix} 1 & 0 & -1 \\ -3 & 6-\lambda & -3 \\ 1 & -3 & 2-\lambda \end{vmatrix} = 0$$

$$\left. \begin{array}{l} C_1' = C_1 + C_3 \\ C_2' = C_2 \\ C_3' = C_3 \end{array} \right\} \rightarrow (1-\lambda) \begin{vmatrix} 0 & 0 & -1 \\ -6 & 6-\lambda & -3 \\ 3-\lambda & -3 & 2-\lambda \end{vmatrix} = (-1)(1-\lambda) \begin{vmatrix} -6 & 6-\lambda \\ 3-\lambda & -3 \end{vmatrix} = 0$$

$$= -(1-\lambda)[18 - (3-\lambda)(6-\lambda)] = -(1-\lambda)[\lambda^2 + 9\lambda] = 0$$

$$= -\lambda(1-\lambda)(\lambda+9) = 0$$

So the eigenvalues of $\underline{A}$ are $\lambda = 0, 1, 9$.

To find the eigenvector corresponding to eigenvalue $\lambda = 1$, we must solve the system of equations $\underline{A}\underline{x} = \lambda\underline{x}$, which may be written $(\underline{A} - \lambda\underline{I})\underline{x} = \underline{0}$

When $\lambda = 0$ we must therefore solve the system

$$\begin{array}{ll} 2x - 3y + z = 0 & (1) \\ -3x + 6y - 3z = 0 & (2) \\ x - 3y + 2z = 0 & (3) \end{array}$$

$$3 \times (1) + (2) \rightarrow 3x - 3y = 0 \rightarrow y = x$$

$$\text{Subs into (1)} \rightarrow 2x - 3(x) + z = 0 \rightarrow z = x$$

[Note: equation (3) is automatically satisfied by $y=x, z=x$ for all x] Hence the eigenvector corresponding to eigenvalue $\lambda = 0$ is $\underline{v}_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ and $t \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ is a solution of the system for all t .

Question 14 solution continued

When $\lambda=1$ we must solve the system

$$x - 3y + z = 0 \quad (4)$$

$$-3x + 5y - 3z = 0 \quad (5)$$

$$x - 3y + z = 0 \quad (6)$$

[notice that equations (4) and (6) are identical]

$$3 \times (4) + (5) \rightarrow -4y = 0 \rightarrow y = 0$$

$$\text{sub. into (4)} \rightarrow x - 3(0) + z = 0 \rightarrow z = -x$$

Hence the eigenvector corresponding to eigenvalue $\lambda=1$ is

$$v_2 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$$

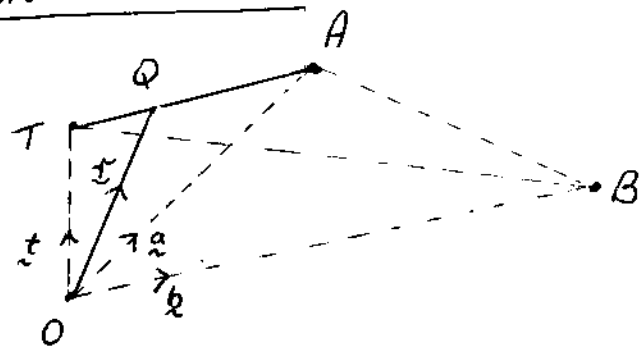
and

$$t \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$$

is a solution of the system

for all t .

Question 15 solution



Let the position vectors of the points T, A and B be $\underline{t}$, $\underline{a}$ and $\underline{b}$ respectively. It is given that $\underline{t} = (2, 2, 0)$, $\underline{a} = (4, 3, 1)$ and $\underline{b} = (-3, 1, 2)$.

a) Let the position vector of Q be $\underline{r}$ then

$$\underline{r} = \underline{t} + \vec{TQ}$$

where $\vec{TQ} = \frac{2}{5} \vec{TA}$.

$$\vec{TA} = \underline{a} - \underline{t} = (4, 3, 1) - (2, 2, 0) = (2, 1, 1) \text{ so } \vec{TQ} = \frac{2}{5}(2, 1, 1) = \left(\frac{4}{5}, \frac{2}{5}, \frac{2}{5}\right),$$

and therefore $\underline{r} = (2, 2, 0) + \left(\frac{4}{5}, \frac{2}{5}, \frac{2}{5}\right) = \left(\frac{14}{5}, \frac{12}{5}, \frac{2}{5}\right)$.

b) The plane π is perpendicular to the vector $\underline{p} = \vec{TA} \times \vec{TB}$

and the equation of π is $\underline{r} \cdot \underline{p} = \text{const.}$

We have already found that $\vec{TA} = (2, 1, 1)$,

$$\vec{TB} = \underline{b} - \underline{t} = (-3, 1, 2) - (2, 2, 0) = (-5, -1, 2)$$

$$\text{so } \underline{p} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 2 & 1 & 1 \\ -5 & -1 & 2 \end{vmatrix} = \underline{i}(2+1) - \underline{j}(4+5) + \underline{k}(-2+5) = (3, -9, 3)$$

The equation of π is therefore $\underline{r} \cdot (3, -9, 3) = \text{const} = c$ (say)

$$\text{i.e. } 3x - 9y + 3z = c$$

The plane passes through T so $3(2) - 9(2) + 3(0) = c$

which gives $c = -12$. (The plane also passes through A and B so we could substitute the coordinates of these points into the equation to find c)

The equation of π is therefore $3x - 9y + 3z = -12$

which can be reduced to

$$\underline{x - 3y + z = -4}$$

Question 15 solution continued

c) If we write the equation of π $\vec{x} \cdot \hat{p} = d$ then $|d|$ is the perpendicular distance of the origin from π .

$$x - 3y + z = -4 \quad \rightarrow \vec{x} \cdot \left(\frac{1}{\sqrt{11}}, -\frac{3}{\sqrt{11}}, \frac{1}{\sqrt{11}} \right) = -\frac{4}{\sqrt{11}}$$

so $\frac{4}{\sqrt{11}}$ is the perpendicular distance of 0 from π .

Question 1b solution

a) R_1 and R_2 will collide if there is a time t for which
 $\vec{r}_1(t) = \vec{r}_2(t)$

$$\text{ie } (t^2, 2t, 5) = (4t-3, 2t^2, 5)$$

Two vectors are equal if their components are equal

$$\begin{array}{lcl} \text{ie } \hat{i} : & t^2 = 4t-3 & \rightarrow t^2 - 4t + 3 = 0 \rightarrow (t-3)(t-1) = 0 \\ \hat{j} : & 2t = 2t^2 & \rightarrow t = 0 \text{ or } t = 1 \\ \hat{k} : & 5 = 5 & \end{array}$$

the $\hat{i}$ components are equal and the $\hat{j}$ components are equal only when $t=1$. Hence the rockets collide at $t=1$.

$$(i) \quad \vec{v}_1 = \dot{\vec{r}}_1(t) = (2t, 2, 0), \text{ at } t=1 \quad \vec{v}_1 = (2, 2, 0)$$

$$\vec{v}_2 = \dot{\vec{r}}_2(t) = (4, 4t, 0), \text{ at } t=1 \quad \vec{v}_2 = (4, 4, 0)$$

$$\text{hence } \vec{v}_2 = 2\vec{v}_1 \quad \text{ie } |\vec{v}_2| = 2|\vec{v}_1| \quad \text{and } \vec{v}_2 = \vec{v}_1$$

$$(ii) \quad \vec{a}_1 = \ddot{\vec{r}}_1(t) = (2, 0, 0) \quad \text{for all } t$$

$$\vec{a}_2 = \ddot{\vec{r}}_2(t) = (0, 4, 0) \quad \text{for all } t$$

$$|\vec{a}_2| = 2|\vec{a}_1| \quad \text{and} \quad \vec{a}_1 \cdot \vec{a}_2 = 0 \quad \text{hence } \vec{a}_1 \perp \vec{a}_2$$

$$b) \quad \begin{array}{l} 2x + 8y + 3z = 0 \quad (1) \\ x + 2y + z = 0 \quad (2) \end{array}$$

$$(1) - 3(2) \rightarrow -x + 2y = 0 \rightarrow y = \frac{1}{2}x$$

$$\text{Subs into (2)} \rightarrow x + 2\left(\frac{1}{2}x\right) + z = 0 \rightarrow z = -2x$$

Hence $y = \frac{1}{2}x$, $z = -2x$ satisfy the equations for all values of x . The solution is therefore the set of values of (x, y, z) on the straight line

$$x = \lambda, \quad y = \frac{1}{2}\lambda, \quad z = -2\lambda \quad \text{for } -\infty < \lambda < \infty$$

The line passes through the origin. The vector equation of the line is

$$\vec{r} = \vec{0} + \lambda(1, \frac{1}{2}, -2)$$

$$\text{ie } \vec{r} = \lambda(1, \frac{1}{2}, -2) \text{ for } -\infty < \lambda < \infty$$

Question 16 Solutions continued

Let the points on the line L_1 be labelled $\underline{r}_1$ and the points on line L_2 be labelled $\underline{r}_2$, then

$$\underline{r}_1 = \lambda(1, \frac{1}{2}, -2) \quad \text{and} \quad \underline{r}_2 = (1, 2, 3) + \mu(1, 1, -\frac{1}{3})$$

L_1 and L_2 intersect when $\underline{r}_1 = \underline{r}_2$ ie we must find the values of λ and μ for which $\underline{r}_1 = \underline{r}_2$.
Comparing components in the equation $\underline{r}_1 = \underline{r}_2$ we have

$$\hat{i}: \quad \lambda = 1 + \mu \quad (1)$$

$$\hat{j}: \quad \frac{1}{2}\lambda = 2 + \mu \quad (2)$$

$$\hat{k}: \quad -2\lambda = 3 - \frac{1}{3}\mu \quad (3)$$

$$(1) - (2) \rightarrow \frac{1}{2}\lambda = -1 \quad \text{so} \quad \lambda = -2$$

$$\text{Subs into (1)} \rightarrow \mu = -3$$

Note: Equation (3) is automatically satisfied.

Hence the lines intersect at $(-2, -1, 4)$

$$\text{(ie. } \underline{r}_1 = -2(1, \frac{1}{2}, -2), \quad \underline{r}_2 = (1, 2, 3) - 3(1, 1, -\frac{1}{3}) \text{)}$$